



EPSRC Centre for Doctoral Training in Agri-Food Robotics

Development <u>and</u> Evaluation of a Low-Cost, 3D-Printed Robotic Head for Plant Monitoring in Greenhouse Environments

Andrew Simpson^{*} (AgriForWard CDT Student) Grzegorz Cielniak[‡] (Lincoln Institute for Agri Food Technology)

Sub-Saharan Africa is grappling with critical challenges in food security, exacerbated by an increasing population and climatic unpredictability such as droughts and flooding [1]. Traditional farming practices may benefit from innovative, climate-resilient agricultural Kenya's adoption remains low often due to high setup costs and limited technical know-how.

Introduction

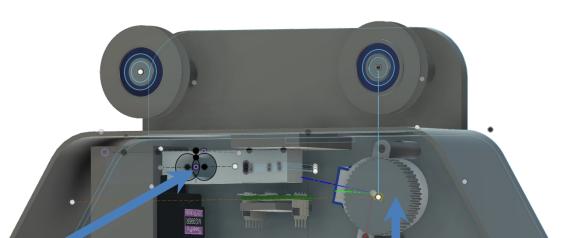


Why it Matters

Methodology

Experimental Design

- Controlled Simulation with Real Plant Pots
 Data Collection
- Weighing Accuracy



- **Movement Efficiency**
- Modularity Assessment
- Cost and Adaptability

Data Analysis

- Statistical Analysis
- Feasibility and Modularity Analysis
- Cost-Benefit Analysis

Preliminary Findings

Weighing System

Comparative analysis with calibrated kitchen scales **Movement Efficiency** Time taken for movement along the overhead wire track. **Modularity and Extensibility** Discussion on the ease of

Strain gauge

ESP32-CAM to monitor & image capture

Stepper (drive) motor

Weigh hook to lift plants

<figure>

Objectives

Food Security Concerns in Sub-Saharan Africa

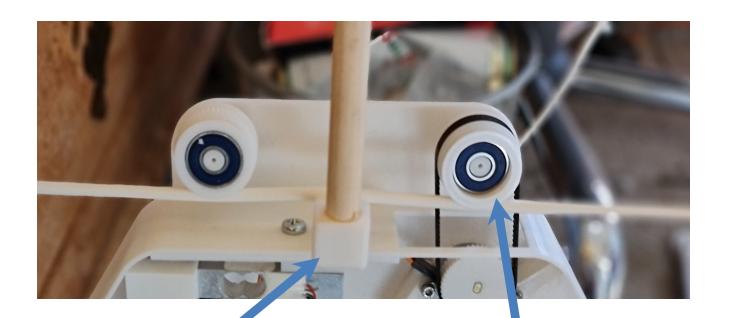
Crop care involves repetitive and timeconsuming tasks which can be automated [2].

Climate-related Challenges in Farming Limited Adoption of Greenhouse Technology in Kenya [3]

An Affordable Automated Crop Care







Approach for Small-Scale Farms in Sub-Saharan Africa

The aim of this research is to evaluate the effectiveness and extensibility of a low-cost, 3Dprinted, robotically-controlled head for monitoring and managing plants in a simulated greenhouse environment. adding functionalities like humidity sensors, cameras, etc. **Cost and Adaptability** Cost analysis and potential for real-world applications. "Inv

"Invisible" cable supports

Combined drive/pulley wheel

Research Question(s)

"How effective and extensible is a low-cost, 3D-printed, robotically-controlled head for monitoring and managing plant care in a simulated greenhouse environment?"

Sub-Questions

What weighing accuracy can be expected? Movement Efficiency, e.g. slippage, derailment, cable sag

Sub Future Work/Conclusions and Outlook

Other sensor modules, how easily can the head unit be upgraded?

e contraction of the second se

farmers on the ground to establish need (if any). Extending functionalities to include more plant health variables such as soil moisture and temperature.



Design Modularity: how easily can other sensors be added Cost-effectiveness and Adaptability; Built and maintained locally?

References

[1] M. Armstrong. "Africa Is on the Frontline of Climate Change." statista.com. <u>https://www.statista.com/chart/28136/index-scores-for-climate-resilience-of-african-countries/</u>

[2] G. Bagagiolo, G. Matranga, E. Cavallo, and N. Pampuro, "Greenhouse Robots: Ultimate Solutions to Improve Automation in Protected Cropping Systems—A Review," Sustainability, vol. 14, no. 11, doi: 10.3390/su14116436.

[3] Sanzua L. J , Saha H. M , Mwafaida J , "Status of Greenhouse Farming in the Coastal Humid Climatic Region of Kenya," Universal Journal of Agricultural Research, Vol. 6, No. 5, pp. 165 - 172, 2018. DOI: 10.13189/ujar.2018.060504.

Exploring the addition of watering and nutrient-feeding systems.

Collaborate and work with

Collaborators

*Agriforwards CDT, Department of Engineering (University of Cambridge)
 ‡ Agriforwards CDT, Robotics Department, University of Lincoln

Evaluate in live settings, to test for factors such as humidity, dust, accuracy and ease of track installation



Engineering and Physical Sciences Research Council





